Estimates of beta-beating for 2015.

Andy Langner, Rogelio Tomas

European Organization for Nuclear Research (CERN) & Universität Hamburg

LCU meeting, 13.12.13

Acknowledgments: N. Aquilina, M. Giovannozzi, P. Hagen, E. Todesco







Outline.

- Beta-beat estimates at 7 TeV
 - Missing MQT magnets
 - Dipole b2 errors
 - Fringe fields
 - Hysteresis and saturation
 - MQX saturation
 - Extrapolation from 2012 local corrections
- Improvements in correction techniques



Beta-beat estimates.

Missing MQT magnets.

- MQT 18.L1 is broken
- The disabled magnet can be compensated by increasing the strength of the other MQTs in this arc
- Switching off 4 MQTs is a favored solution for keeping low beta-beat and low dispersion-beat



Injection optics at 7 TeV - Missing MQT magnets.

• Tune shift of 0.08 applied

 Global beta-beat is negligible if 4 MQTs are switched off

 Only around these MQT positions a larger beta-beat is observed



 \rightarrow 2% peak beta-beat (in arc81, negligible elsewhere)

ATS 20cm optics at 7 TeV - Missing MQT magnets.



→ 4% peak beta-beat (in arc81, negligible elsewhere)

Dipole b2 errors.

• Nominal optics (0.4/10/0.4/3)



ATS 0.2m optics

 \rightarrow 3-10% peak beta-beat

Fringe fields of triplet magnets.

- Measured values of gradient versus longitudinal coordinate for MQXF magnets
- Applied on MQXA and MQXB by scaling with aperture (D)
- Fringe field fall off described by Enge function:



Fringe fields of triplet magnets.

- 0.5m on each end of the magnet is modeled using the fringe field fit
- 50 slices of 10cm length on both ends
- the mid part of the magnet has the same k value as before but length is changed in order to achieve the same overall *k* · *L*



9/26

Fringe fields of triplet magnets.



Hysteresis at 7 TeV.

- FiDeL model describes ramp up branch
- This causes an error for magnets which are ramped down, e.g. during the squeeze
- 30 magnets from the MQY, MQM and MQML family

→ 0.5% peak beta-beat



Saturation and hysteresis at 7 TeV (squeeze).

- Saturation uncertainties are treated statistically
- Simulation of 60 cases with random gradient errors following a Gaussian distribution within the saturation uncertainty
- Considered magnet types: MQ, MQY, MQM, MQML, MQMC and MQW



→ 1% peak beta-beat

Saturation and hysteresis at 7 TeV (squeeze).

- Saturation uncertainty of triplet magnets MQXA and MQXB is now added to the simulation
- Strongest contribution to the beta-beat from these magnets



ightarrow $m \approx$ 60% peak beta-beat in worst case scenarios

Extrapolation from 2012 local corrections.

- Local corrections for $\beta^* = 0.6 \text{ m}$ (from 2012) \rightarrow 80% peak beta-beat
- Extrapolation to 0.4 m from known local corrections plus b2 errors → 100% peak beta-beat



Estimated beta-beat from combining all aforementioned error sources.



ightarrow 160% peak beta-beat in worst case scenarios

Summary from beta-beat estimates.

Missing MQT magnets

→ 2-4% peak beta-beat (in arc81, negligible elsewhere)

- Dipole b2 errors
 - → 3-10% peak beta-beat
- Fringe fields of triplets
 - → 1% peak beta-beat
- Hysteresis
 - \rightarrow 0.5% peak beta-beat
- Saturation (w/o triplets)
 → 1% peak beta-beat
- Saturation (with triplets)
 → ≈ 60% peak beta-beat (worst case)
- Extrapolation from measurement at 0.6 m
 → ≈ 100% peak beta-beat
- Approx. beta-beat from combining all error sources
 → ≈ 160% peak beta-beat (worst case)

Improvements of correction techniques.

Segment-by-Segment.



- Transport of optical functions from a BPM position
- Technique for investigating local corrections
- Calculation of optical functions at specific elements
- Uses measured optical function at starting point of simulation

Improvements in measured beta-function accuracy.

- New algorithm for beta-function measurement
- Accuracy has been increased especially in the IRs

Increased

resolution for correction technique

25 Old algorithm New w/o b2 errors 20 Q New including b2 errors Avgerage error of measured 15 in IRs (%) 10 5 0 Injection Flattop Squeeze ATS 20cm

Illustration of Segment-by-Segment.

- Errors in the real machine cause deviation of the phase advance
- Searching for magnet errors that can reproduce the measured deviation
- → Correcting optics with this magnet errors



Systematic errors.

- Errors on the measured β- and α-functions propagate to an error of the phase advance → has not taken into account before
- Error on phase advance has minima which indicates higher sensitivity at specific locations
- → Local corrections might be better constrained by using 2 segments with starting location separated by $\approx 90^{\circ}$



Example for error bar improvement.



Impact of fringe fields on Segment-by-Segment.





- Monte-Carlo Approach to fit optics to measured constraints
- Vary quadrupole strengths $\Delta k \rightarrow \frown$ and long. positions Δs



 \rightarrow Variation of simulated phase advances $\Delta \Phi_{i,Sim}$

• Minimize
$$\chi^2 = \sum_i \left(\frac{\Delta \Phi_{i,Meas} - \Delta \Phi_{i,Sim}}{\sigma(\Delta \Phi_i)} \right)^2$$

A. Langner (CERN)

Offline correction technique.

- Flexible technique
 → can be
 combined with
 other
 measurements
 (k-modulation)
- This method was tested in IR1 in combination with constraints from ALFA detector measurements



Summary of improvements in correction techniques.

- beta-function measured with higher accuracy
 - → Higher precision of Segment-by-Segment
- Code will be extended to use combine start location for the simulation
 → Sensitivity for different error sources
- Impact of known model uncertainties will be considered (Fringe fields, MQT, b2...)
- Monte-Carlo approach for offline corrections