

**ORBIT DISTORTION AT TRANSITION  
CROSSING WITH A NEW PICK-UP IN  
SS76 IN THE CERN PS**

**Sandra Aumon - Heiko Damerou - Simone Gilardoni**

**BE/ABP - LIS Meeting**

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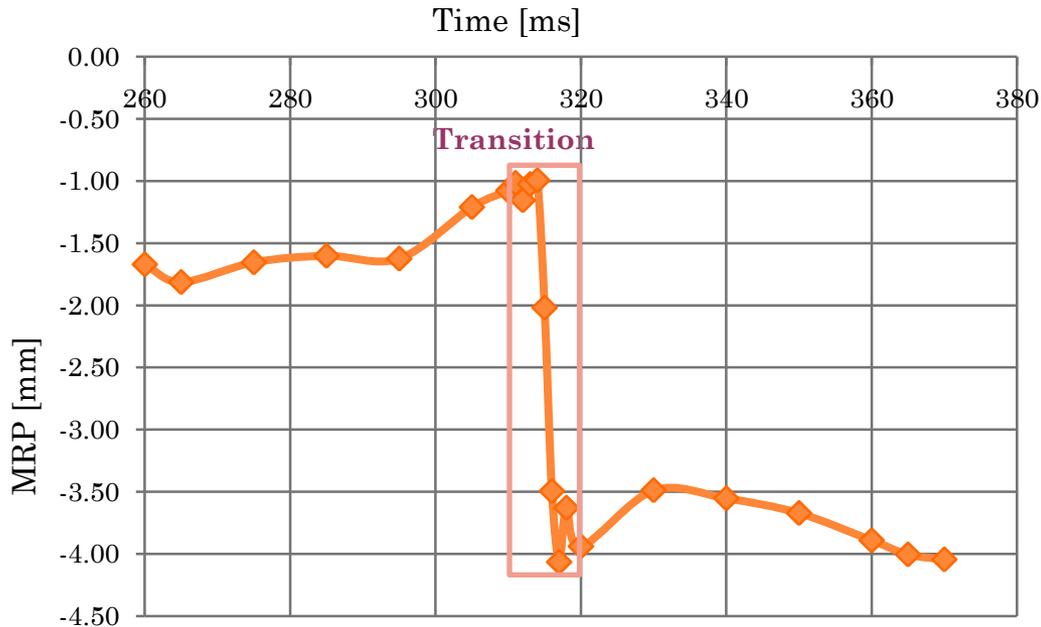
# CONTENTS

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- Motivations: MRP through transition in 2007.
- The radial loop control system (RLC).
- Trajectory through transition with the new CODD
- Disadvantages of the current RLC configuration.
- Motivations for the choice of the new RLC config.
- MD – What did we do – Results
- Conclusions - Outlooks

# MEAN RADIAL POSITION @ TRANSITION (2007)

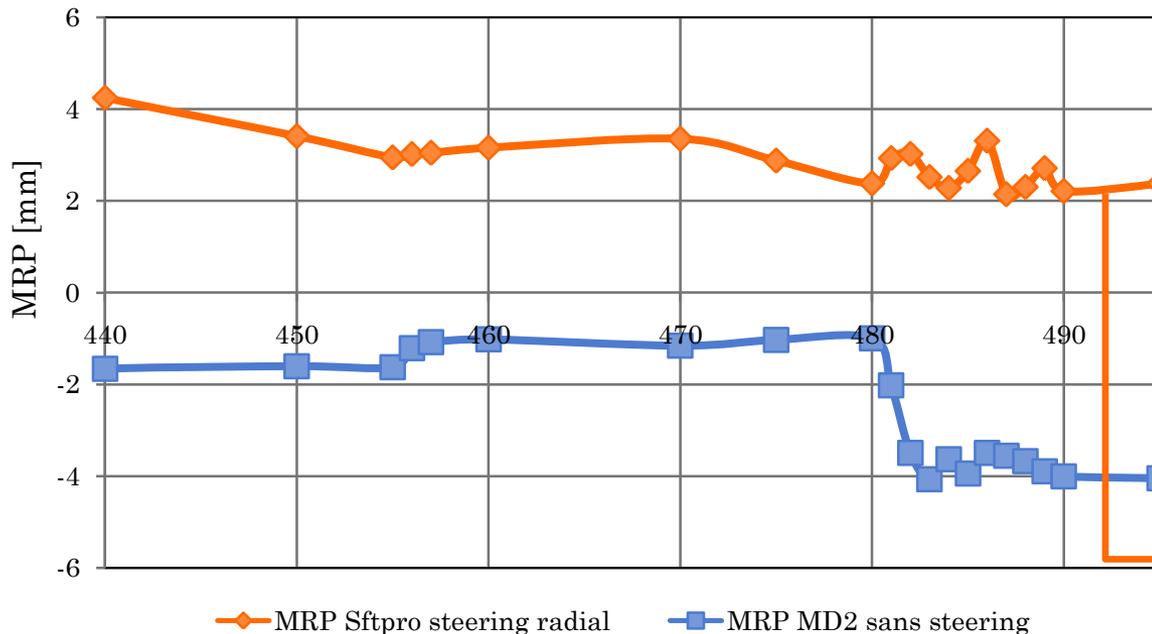
Mean Radial Position (MRP) computed with the 40 PUs of the orbit measurement system (CODD) with an AD beam



- MRP-jump due to the doublets inversion of the Gammajump.
- 1-2 mm of the jump is explained by the fact that the orbit doesn't pass by the center of the GJ quadrupoles
- However, 2mm are left.

# MRP WITH A RADIAL STEERING

SFTPRO 10/10/07, Transition time: 486 ms



- Radial steering of +3.5mm along the Gammajump

- Triplets of the Gammajump are debalanced

Beam passes by the center of the quadrupoles

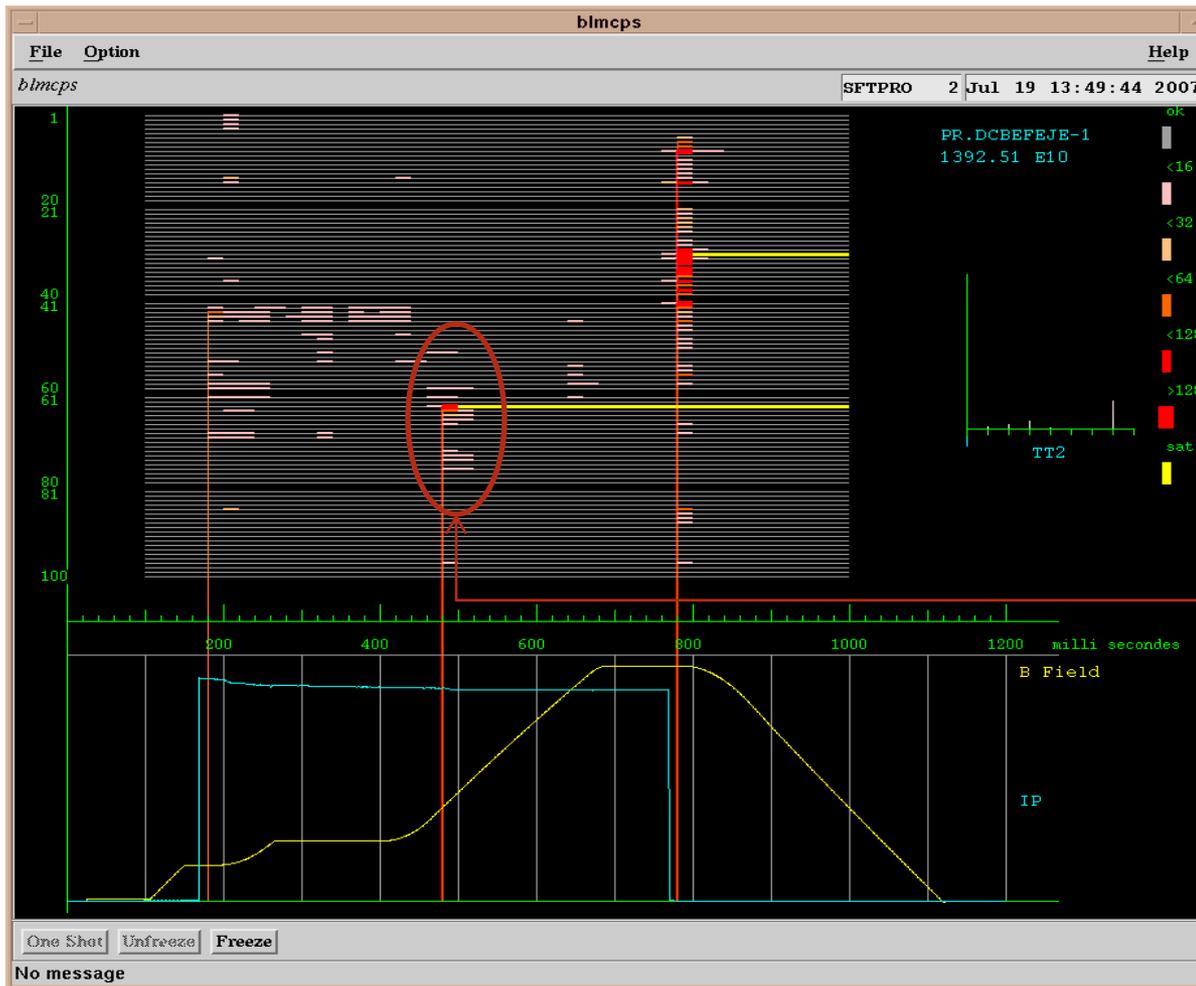
With the radial steering:

- Less losses.
- No MRP jump at transition

# MRP WITH A RADIAL STEERING

- BLM SFTPRO 2 Juillet 2007 – sans correction

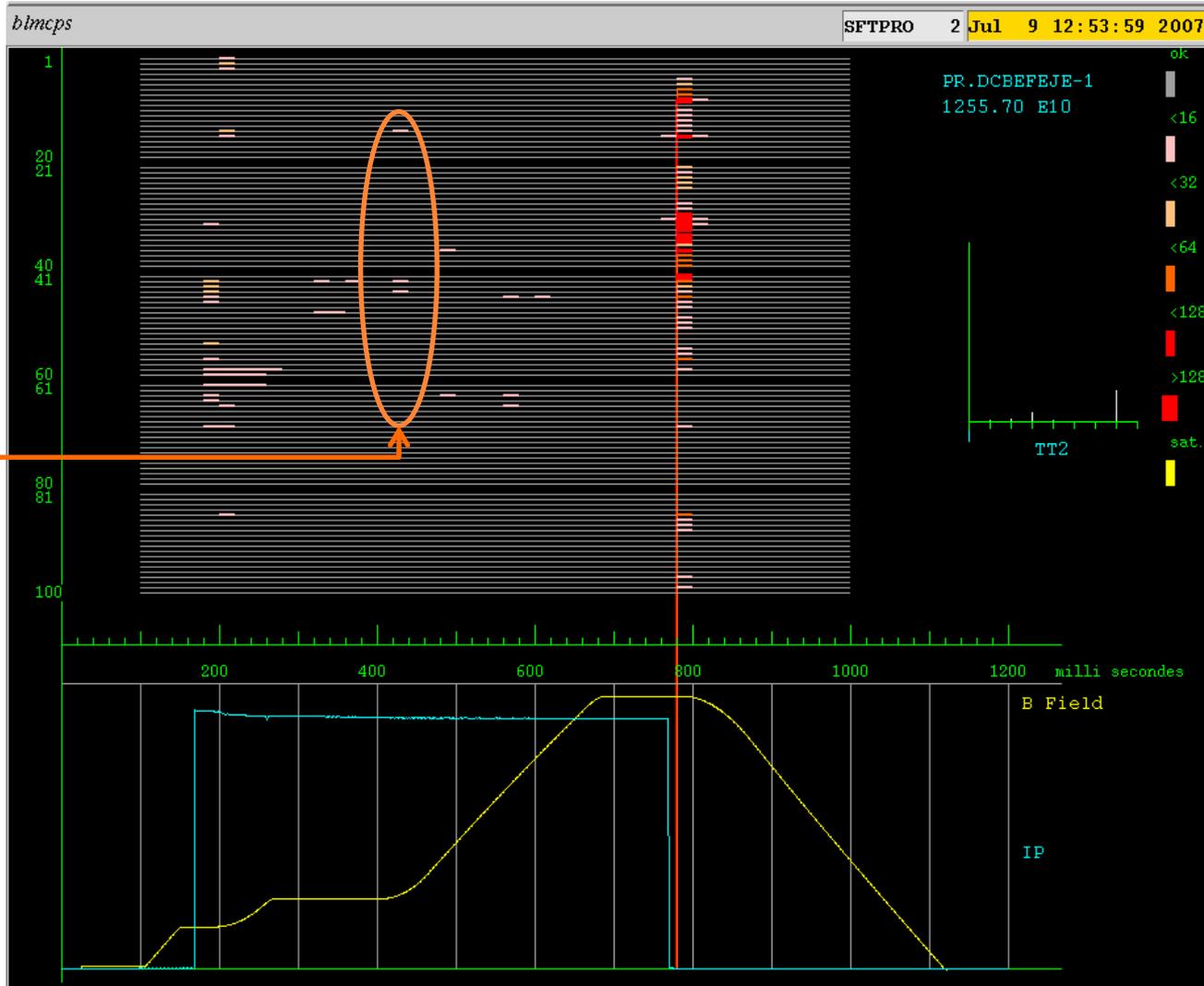
SFTPRO: 1392 e10 part



Environ 1-2% du faisceau est perdu  
~ 10-20 e10 part.  
~ faisceau EAST

Transition

# MRP WITH A RADIAL STEERING



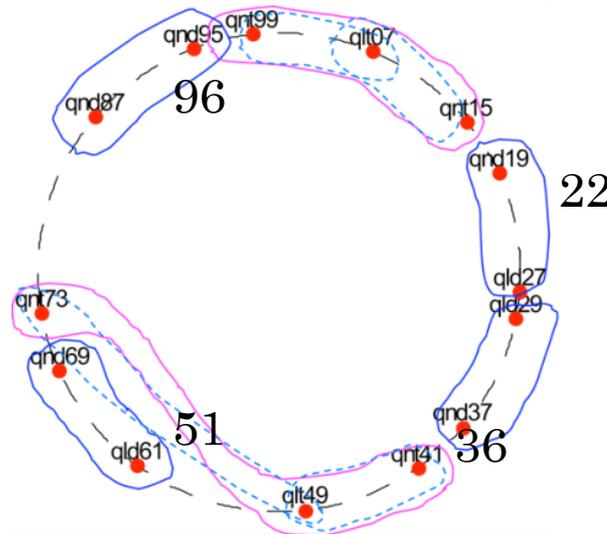
*Transition*

0.2% de  
perte,  
avec la  
correction

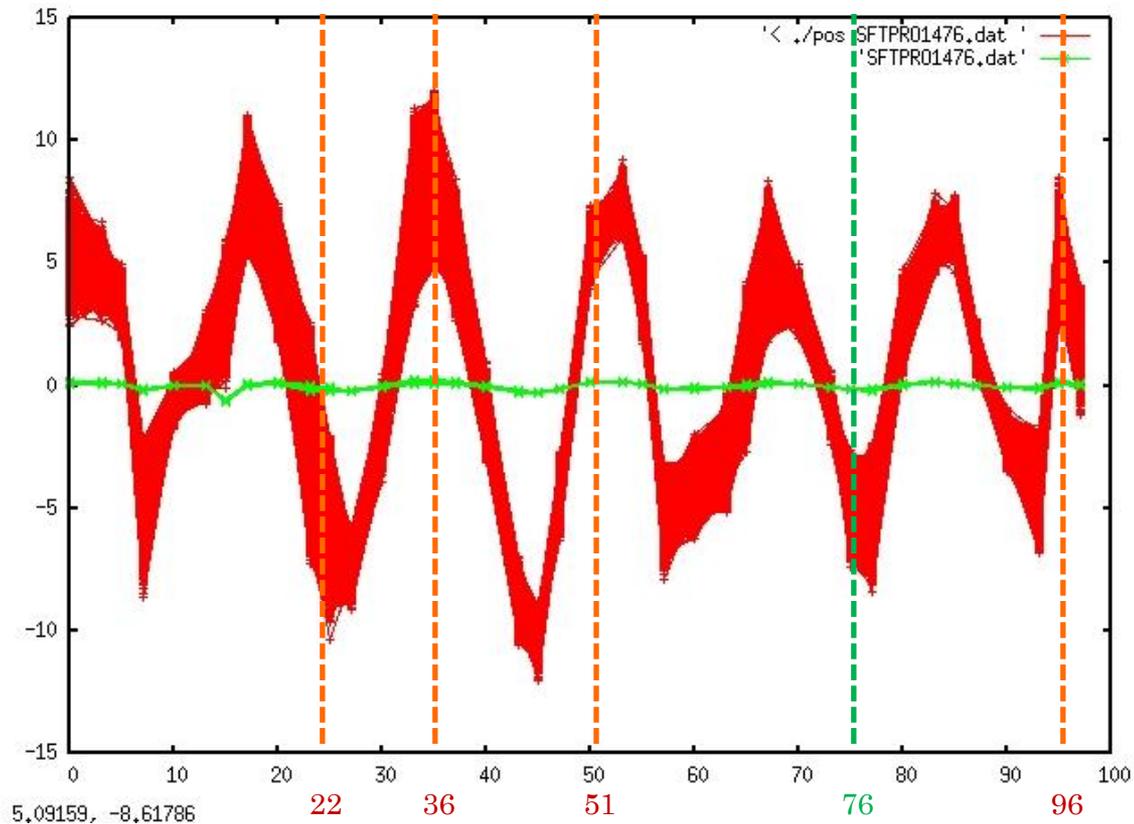
# RADIAL LOOP SYSTEM

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- The radial loop system controls the MRP with initially 3 PUs in section 22-51-96. The PU 36 was included in 2008.
- It is working jointly with the phase loop.



# TRAJECTORY THROUGH TRANSITION



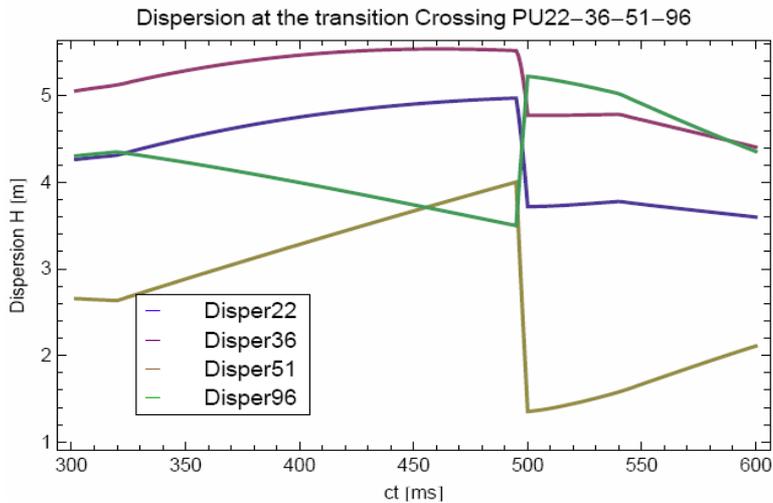
Data taken with the new orbit measurements system (10000 trajectories through transition)

From J. Bellemann

Phase advance not suitable

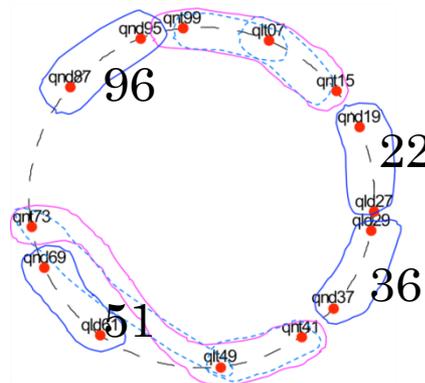
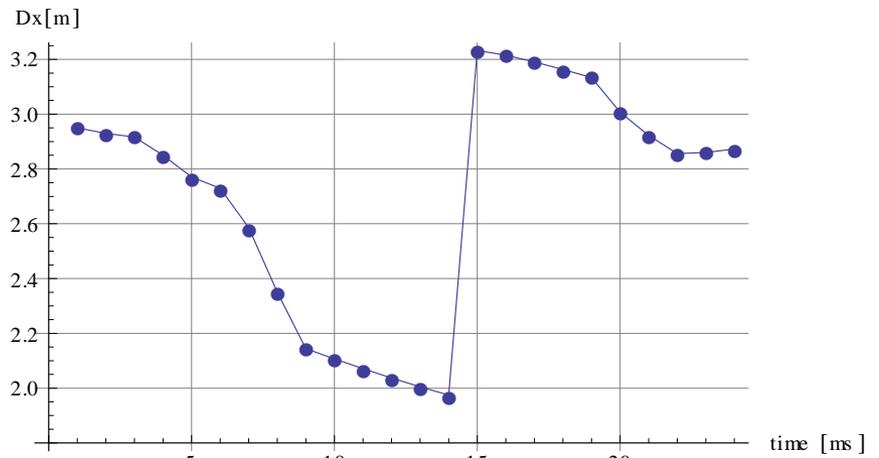
# DISPERSIONS THROUGH TRANSITION

## Dispersion at 4 PUs



- The PU51 might be less sensitive to changes in trajectory due to dispersion.
- Dispersion computed with MADX

## Mean Dispersion in the PS

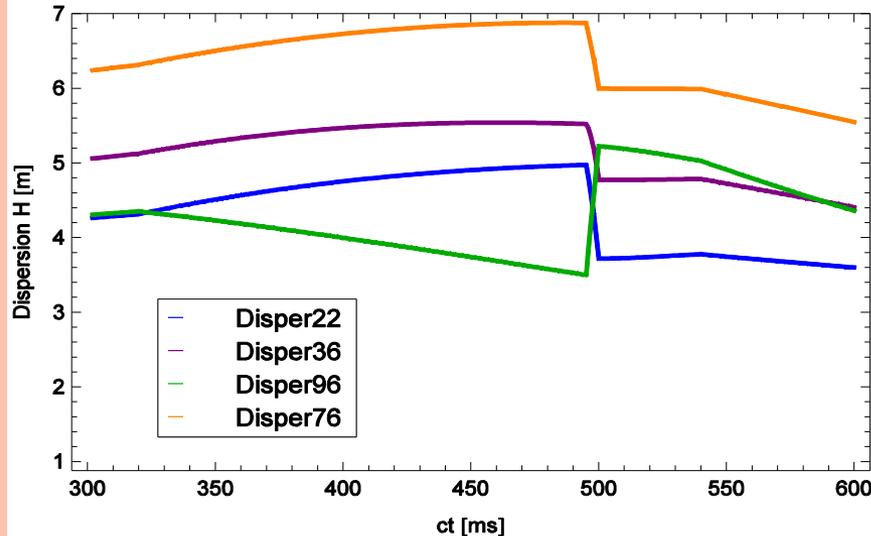


# PROBLEMS WITH THE CURRENT SYSTEM

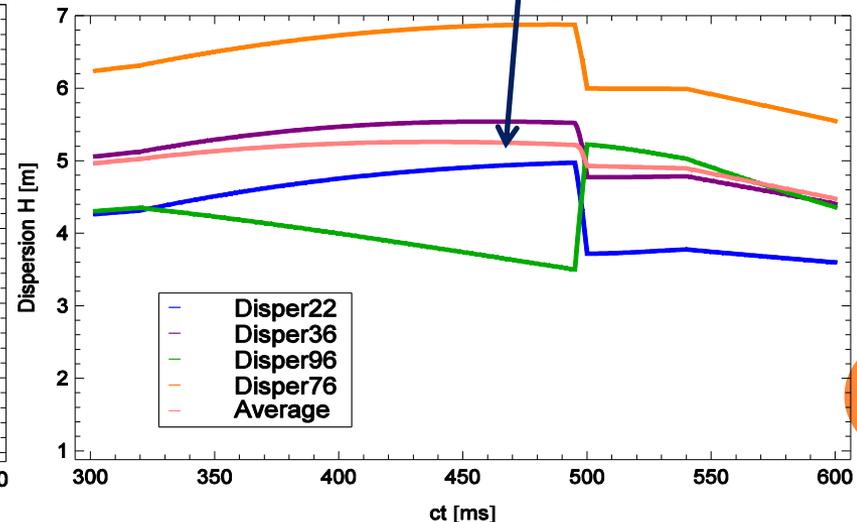
- PU51 is less sensitive to changes in trajectory due to its low dispersion during the Gammajump.
- Not optimal phase advance between the PU51 and 96 and PU36.
- Proposal to include the PU76 in the radial loop system

With dispersion average @ the Pus 22-36-96-76

Dispersion at the transition Crossing PU22-36-96-76



Dispersion at the transition Crossing PU22-36-96-76

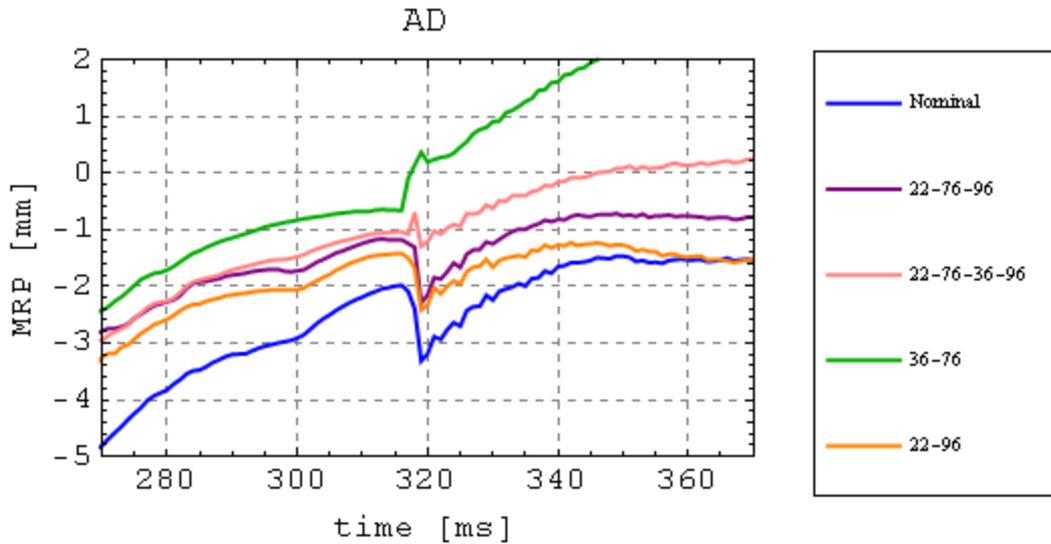


# MRP MEASUREMENTS WITH THE PU76

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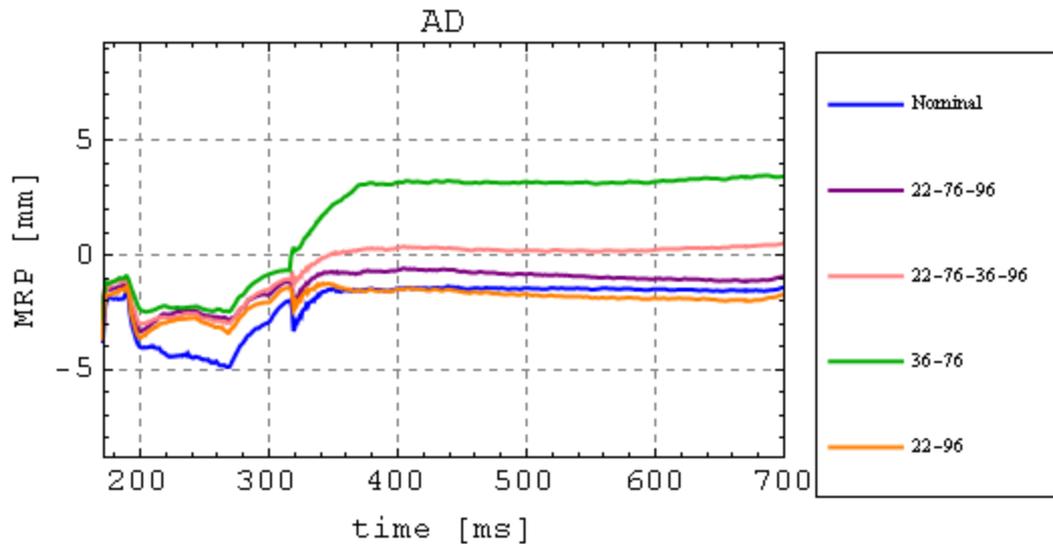
- The PU76 was connected to the radial loop control system.
- MRP measurements on the AD, SFTPRO and ToF beams with several PUs combinations (PU22, 36, 76, 96 and the current configuration)
- Trajectories turn by turn thanks to the new orbit measurements system.

# RESULTS MD – AD BEAM

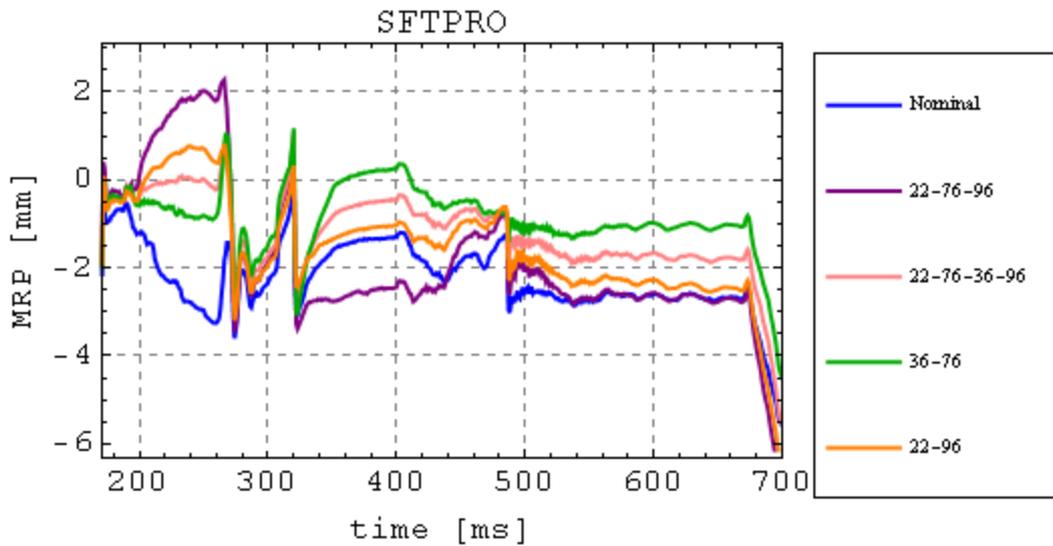


MRP @ transition and along the cycle.

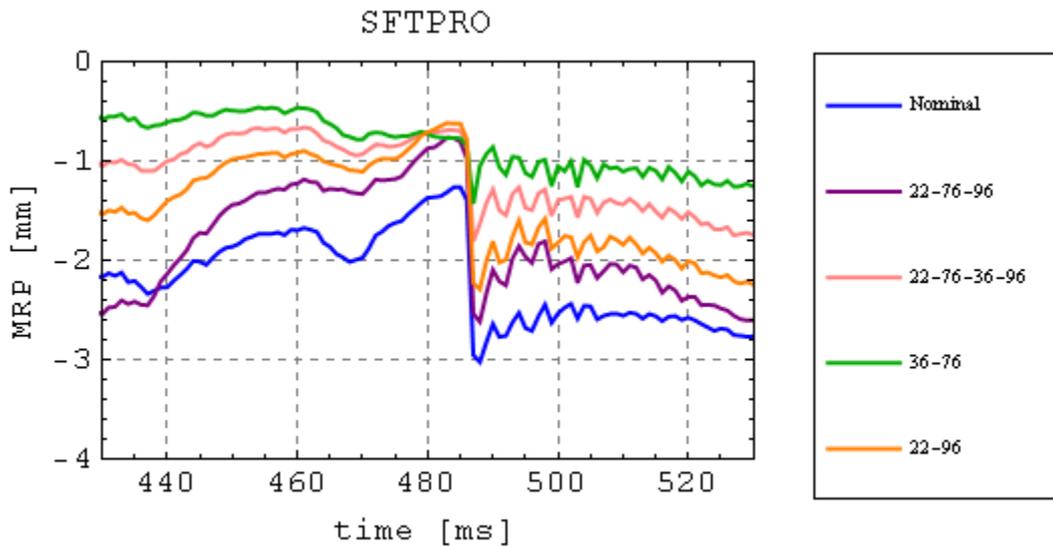
- Beam well centered for 22-36-76-96
- Almost no MRP jump
- Mean center of the GJ quadrupoles around -1mm



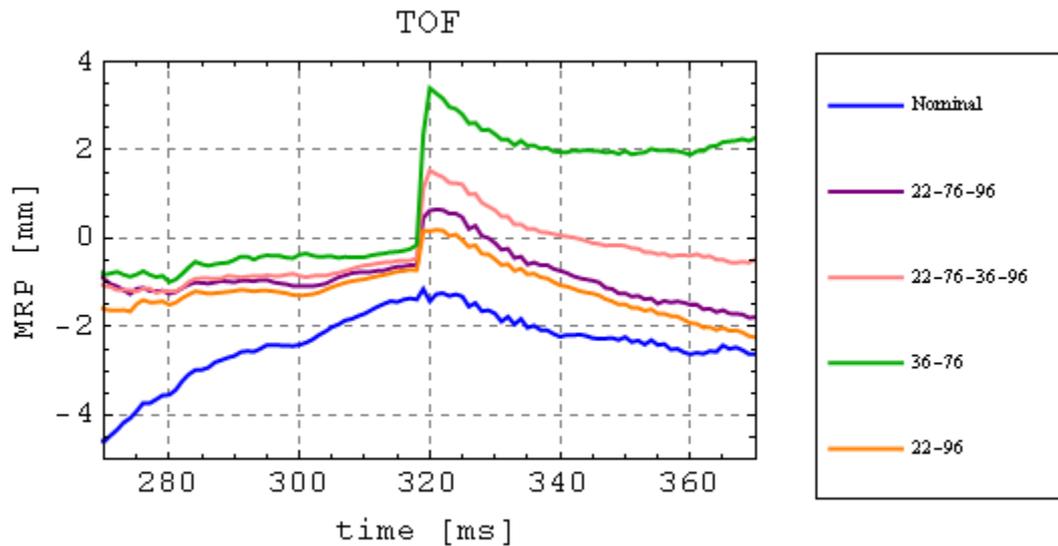
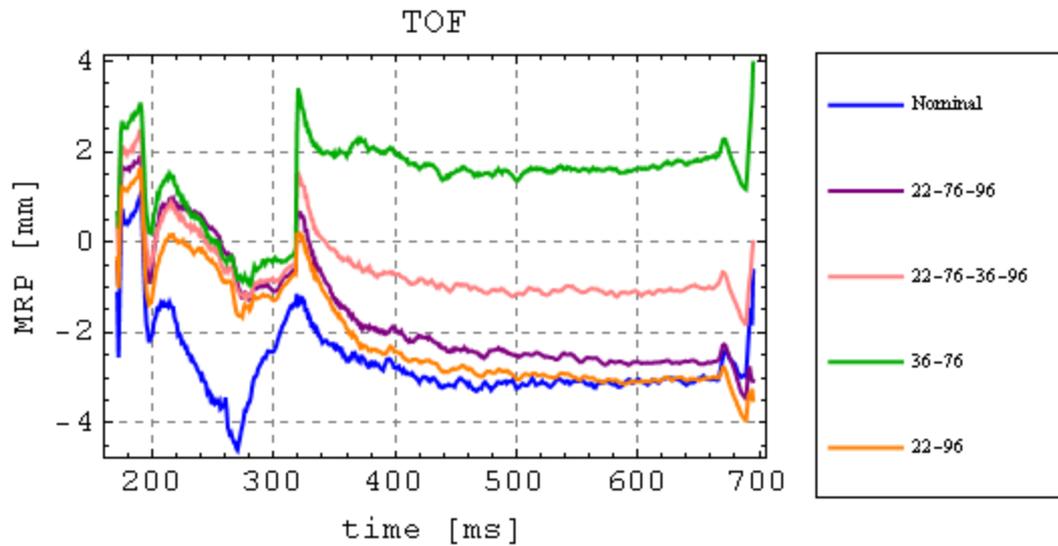
# RESULTS MD – SFTPRO BEAM



MRP @ transition and along the cycle.



# RESULTS MD – TOF BEAM



MRP @ transition and along the cycle.

- Mean center of the beam of the GJ quads  $\sim -1$ mm.
- The direction of the jump is inversed.

# CONCLUSIONS-OUTLOOKS

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- In 2007, the center of the GJ quads seemed to be around +3.5mm. This year, the center seems to be around -1mm.
- Measurements with radial steering to check the transition crossing of the MRP.
- Launch orbit simulations with the new alignment of the GJ quads.
- The steering of the beam had been improved by using the new PU76: the radial loop system is more sensitive to energy error and the Pus have a better advance.
- MRP-jump due to:
  - steering of the beam at the GJ quads (inversion of the doublet @ transition)
  - The radial loop system can not correct quick deviation (doublets inversion  $\sim 500\mu\text{s}$ .), the system is inactive for several ms. This is what we observed