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PROGRAMME DOCTORAL EN PHYSIQUE
DOCTORAL PROGRAM IN PHYSICS



Magnetic Model of the CERN PS Accelerator

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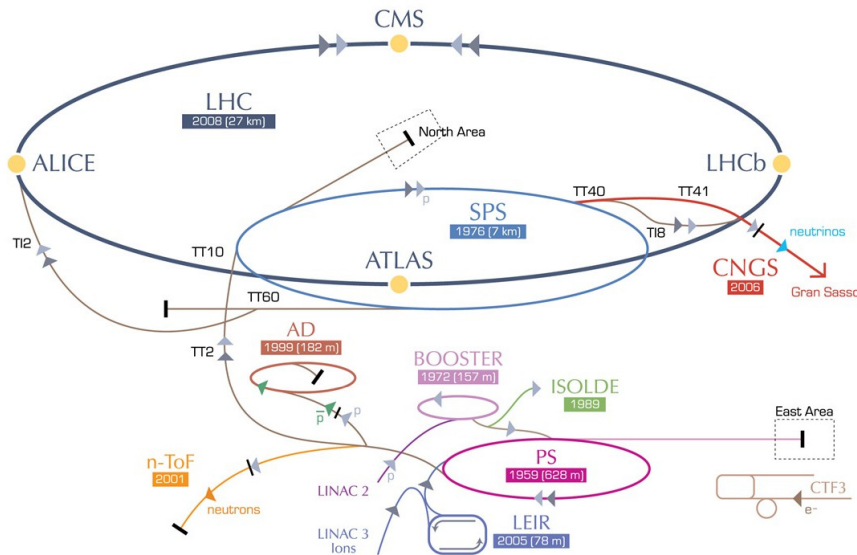


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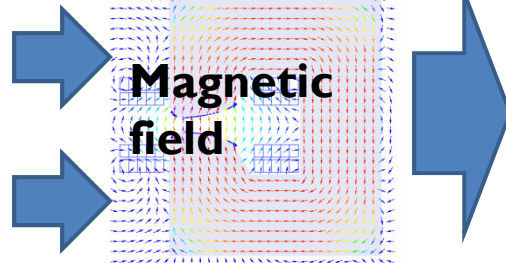
Introduction

CERN's accelerator complex



▶ **Measurements**

▶ **Magnetic model**



▶ **Exploring full potential of LHC physics**

- ▶ Increasing the performance – luminosity
- ▶ Upgrades of the injection chain

▶ **Proton Synchrotron (PS)**

- ▶ Working point adjustments
 - ▶ Reducing beam losses
 - ▶ Increasing beam intensity
- ▶ Control system
 - ▶ Field prediction for power supply control
- ▶ Injection and extraction upgrades
 - ▶ PSB and SPS upgrades
 - ▶ Multi-turn Extraction



Motivation

- ▶ In 50 years of the PS operation all attempts to establish a field model, necessary for machine developments, have failed so far.
- ▶ After the cancellation of the PS2 project, it is now clear the PS will have to provide a reliable and high performance beams, for various working points, for the next 25 years.
- ▶ Setting a field model becomes now a necessity.



Objectives

- ▶ To develop a model of the magnetic field inside the PS magnets, capable of accurately recreating the magnetic field along the beam trajectory.
- ▶ Implement and validate the magnetic model inside existing optical model of the PS accelerator.



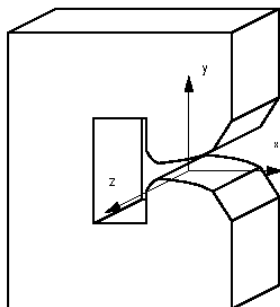
Methodology

- ▶ Investigation of the magnetic field inside the PS magnet
 - ▶ Broad numerical analysis in 2D and 3D (static, transient, demagnetization).
 - ▶ Magnetic measurements (real-time using B-train system, dedicated with spare magnets).
 - ▶ Establish separate contributions of different circuits.
 - ▶ Derive quasi-static formulas of the field components taking into account dynamic and hysteresis effects.
- ▶ Implementation of the magnetic model in the existing optical model of the PS accelerator.
 - ▶ Simulation of the optical parameters with MAD-X model.
 - ▶ Beam-based measurements (tune and chromaticity).
 - ▶ Verification and calibration of the magnetic model.
 - ▶ Optical model enhancements.
- ▶ Investigation of the possibility of implementing the model in the control system of the accelerator

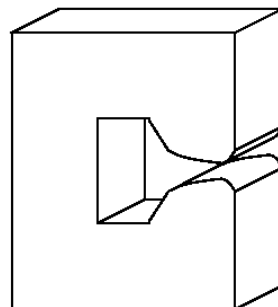
Proton Synchrotron main magnetic unit



Open block



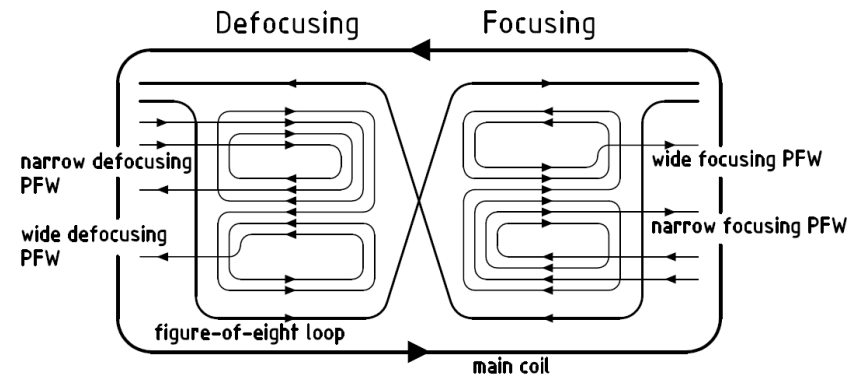
Closed block



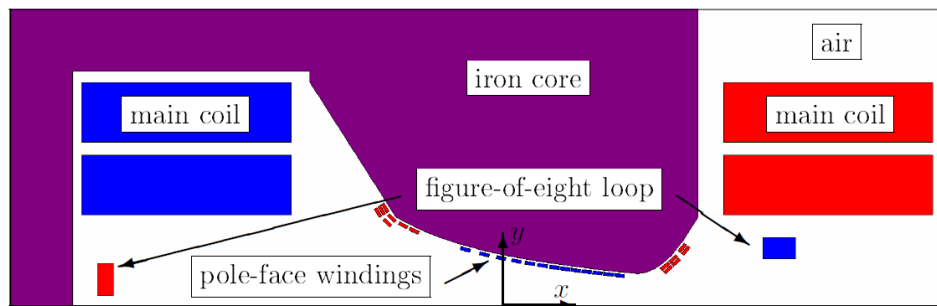
- ▶ Combined-function magnet with hyperbolic pole shape
 - ▶ Dipole field – guiding
 - ▶ Quadrupole field – focusing
 - ▶ Higher component are also present due to saturation
- ▶ Focusing and defocusing half (alternating-gradient focusing)
 - ▶ 5 C-shaped block in each half
 - ▶ Wedge shaped air gaps between blocks
- ▶ Complex geometry of coils system
- ▶ In total 100+1 main units of four different types.

Coils of the PS magnet

- ▶ Main coil
 - ▶ Dipole and quadrupole field mostly
- ▶ Figure-of-eight loop
 - ▶ Adjusts quadrupole field but also contributes to dipole field
- ▶ Pole-face windings (PFW)
 - ▶ Separately for focusing and defocusing half
 - ▶ Each winding has narrow and wide circuit
 - ▶ Corrects higher components of the field



- ▶ PFW Powering upgrade
 - ▶ Five currents (I_{f8} , I_{pFWFN} , I_{pFWFW} , I_{pFWDN} , I_{pFWDW}) instead of four (I_{f8} , I_{pFWF} , I_{pFWD})
 - ▶ Control of the four beam parameters Q_h , Q_v , ξ_h , ξ_v
 - ▶ One current remains free for controlling an additional physical parameter
 - ▶ Possibility of exploring new working points





Work done so far

- ▶ The contributions of separate circuits have been identified by numerical modelling and analysis.
- ▶ This led to the formulation of a « Transfer matrix ».
- ▶ The association and correction of the « Transfer matrix » with physical formulas based on the magnetic circuits is being explored
- ▶ Several machine measurements were performed to validate the formulas and parameters identified so far.

First results

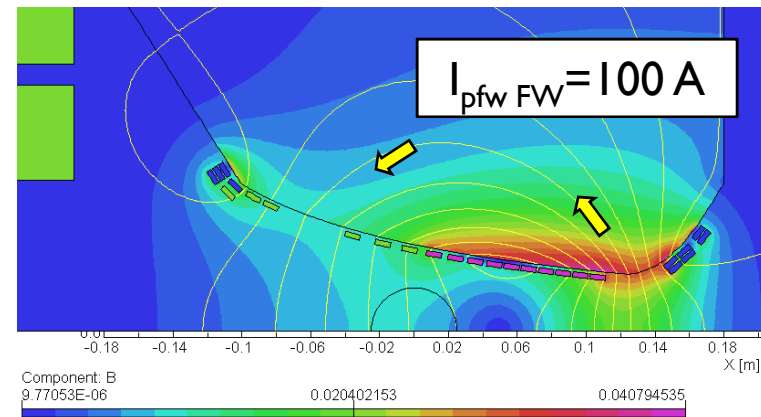
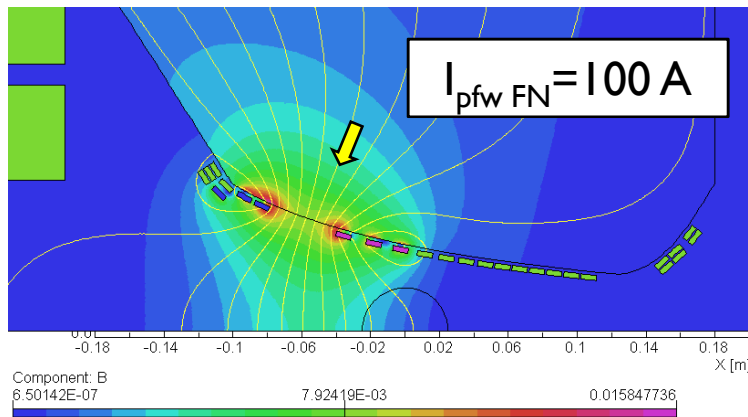
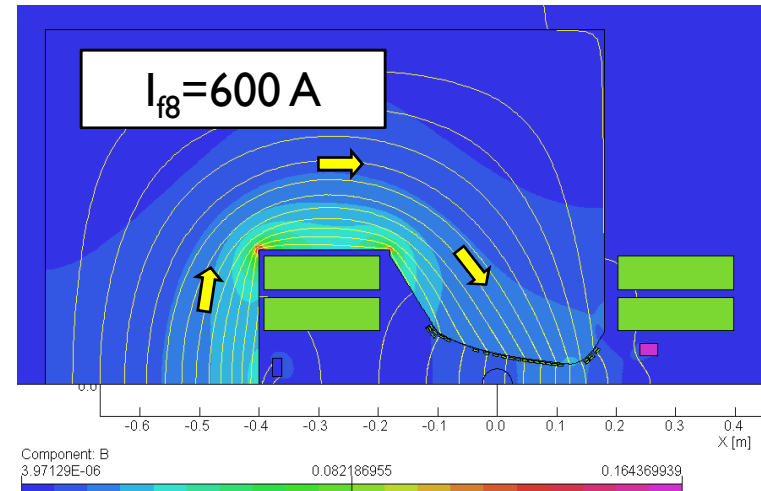
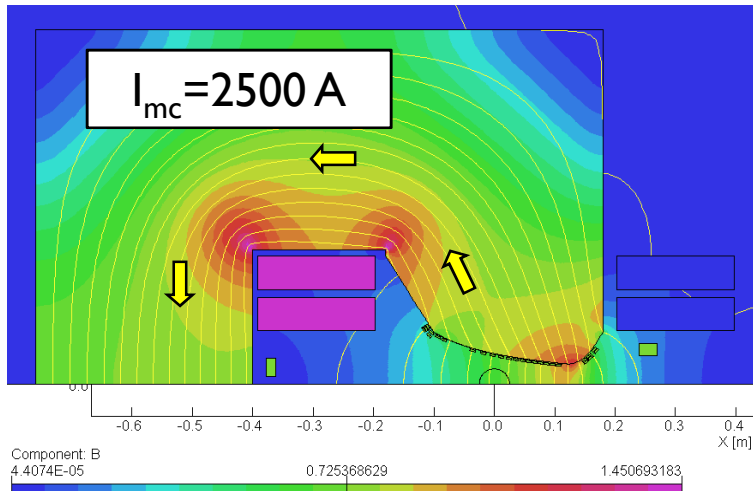
- ▶ The numerical approach seems to be capable of recreating measured data. The requested accuracy may be probably achieved once dynamic and hysteresis effects are implemented.
- ▶ The simplified model set so far could reproduce measurements done in the past on relative variations of the machine tune.



Investigating contributions of separate circuits

- ▶ 2D quasi-static numerical analysis of the magnetic field inside the PS magnet.
- ▶ Range of operations:
 - ▶ Injection $p_{inj} = 2.12 \text{ GeV}/c$
 - ▶ Extraction $p_{extr} = 26 \text{ GeV}/c$
- ▶ Current range:
 - ▶ Main coil $I_{mc} = 400\text{-}5500 \text{ A}$
 - ▶ Figure-of-eight loop $I_{f8} = \pm 1200 \text{ A}$
 - ▶ Pole-face windings $I_{pfw} = \pm 200 \text{ A}$

Investigating contributions of separate circuits



Transfer matrix formulation

- ▶ Decomposed magnetic field in the linear range ($I_{mc} < 3000A$)

$$B_n(I_{mc}, I_{f8}, I_{p_{fwN}}, I_{p_{fwW}}) = p_{n_{mc}} \times I_{mc} + p_{n_{f8}} \times I_{f8} + p_{n_{p_{fwN}}} \times I_{p_{fwN}} + p_{n_{p_{fwW}}} \times I_{p_{fwW}}$$

$n = 1, 2, 3$ corresponds to dipole, quadrupole and sextupole component

- ▶ Transfer matrix with constant contribution coefficients

	Closed (focusing) block			Open (defocusing) block		
	Dipole	Quadrupole	Sextupole	Dipole	Quadrupole	Sextupole
P_{mc}	2.4958E-04	1.0261E-03	-1.1741E-05	2.4959E-04	-1.0266E-03	-1.1253E-05
P_{f8}	-2.4980E-05	-1.0258E-04	-4.9043E-06	2.4980E-05	-1.0251E-04	8.0704E-06
$P_{p_{fwN}}$	-1.6098E-05	6.4759E-04	-1.0835E-02	-1.6098E-05	-6.4759E-04	-1.0836E-02
$P_{p_{fwW}}$	-8.1006E-05	5.6230E-04	4.1829E-02	-8.1007E-05	-5.6223E-04	4.1828E-02

Transfer matrix formulation

- ▶ Behaviour of the magnetic field is not linear
 - ▶ Hyperbolic pole tip
 - ▶ Non-linear magnetic properties
- ▶ $p_n = p_n(I_{mc})$ to increase accuracy
- ▶ Difference between numerically calculated and modelled field using different parameters fitting

	Closed (focusing) block			Open (defocusing) block		
	Dipole [T]	Quadrupole [T/m]	Sextupole [T/m ²]	Dipole [T]	Quadrupole [T/m]	Sextupole [T/m ²]
Constant	6.42e-04	3.23e-03	8.88e-03	6.20e-04	2.32e-03	1.46e-02
Linear	3.83e-04	2.01e-03	7.80e-03	3.84e-04	2.09e-03	8.64e-03
Poly2	9.85e-05	5.39e-04	2.40e-03	9.98e-05	5.16e-04	2.09e-03

- ▶ At higher field level strong non-linear behaviour due to iron saturation
 - ▶ Additional square and cross terms might be introduced
 - ▶ *arctangent* function to fit matrix parameters

Establishing physical formulas

- ▶ Generic formula of the field model

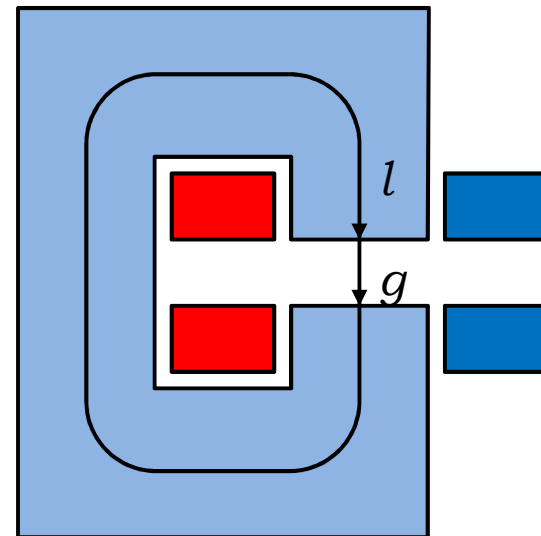
$$B_n = B_n \left(I, \frac{dI}{dt}, t, I(-t) \right)$$

- ▶ Steady field and saturation contribution
- ▶ Remanent field (hysteresis)
- ▶ Dynamic effects (eddy currents)

- ▶ Steady field amplitude

$$B_{gap} = NI \frac{R_{gap}}{R_{core} + R_{gap}} \frac{\mu_0}{g}$$

$$R_{core} = \frac{l}{\mu_{iron} A_{core}}$$



Establishing physical formulas

- ▶ Complete formula for steady field inside the pole gap
 - ▶ Additional formulas for auxiliary circuits
 - ▶ Coupling through the iron permeability
 - ▶ Dependency on horizontal coordinate
 - ▶ Pole gap length
 - ▶ Mean flux path
 - ▶ Iron permeability
 - ▶ Formulas for quadrupolar and sextupolar components

$$G_y = \frac{\partial B_y(x)}{\partial x} \quad S_y = \frac{\partial^2 B_y(x)}{\partial x^2}$$

Performing machine measurements

- ▶ Total field measurement using B-train installation

$$B(t) = B_0 + \int_0^t \dot{B} dt$$

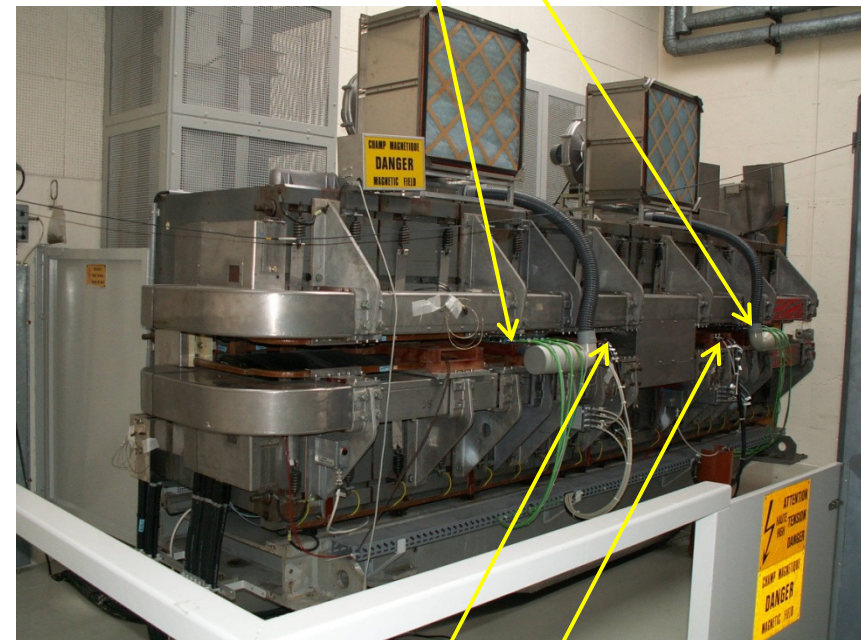
- ▶ Field marker – ”picking-strip”
 - ▶ Saturation of a ferromagnetic strip
 - ▶ $B_0 = 49.8 \text{ G}$
- ▶ Flux coils
 - ▶ Induced voltage $\dot{B} = k \times V_{coil}$
- ▶ Field control using B_{train} signal

$$B_{train} = \frac{0.909 \times B_D + 1.091 \times B_F}{2}$$

- ▶ In scope of this research, possible extension for quadrupole and sextupole measurement

- ▶ Reference magnet

3 × peaking strip (F block)
3 × peaking strip (D block)

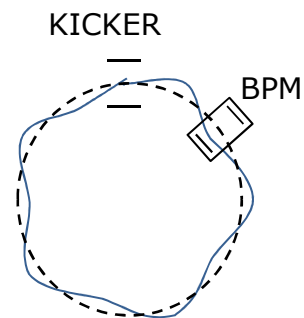


3 × coils (F block)
3 × coils (D block)

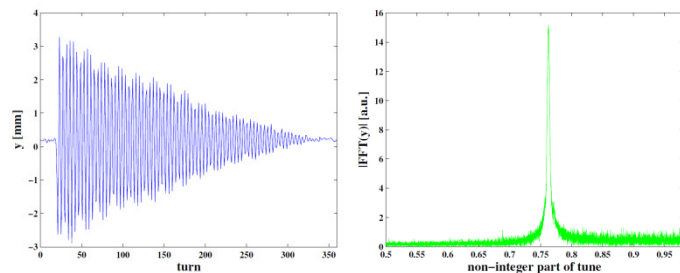
Performing machine measurements

▶ Tune measurements

- ▶ Exciting a coherent betatron oscillation with kicker
- ▶ Measuring beam position with a pick-up

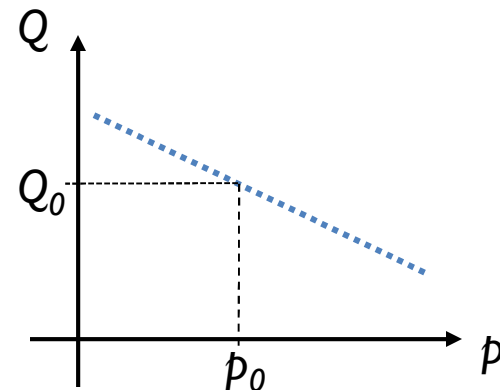


▶ Non-integer part of the tune obtained with Fourier Transform



▶ Chromaticity measurements

- ▶ Modulating beam momentum using RF frequency
- ▶ Tracking tune



$$\frac{\Delta Q}{Q_0} = \xi \frac{\Delta p}{p_0}$$

First comparison with measurement data

- ▶ Powering configuration used in measurements from 1992

	I_{mc}	I_{f8}	I_{pFwF}	I_{pFwD}
Cycle E	669.2 A	0 A	0 A	0 A
Cycle A	2677.5 A	450.35 A	39.05 A	-45.08 A

- ▶ Cycle E comparison

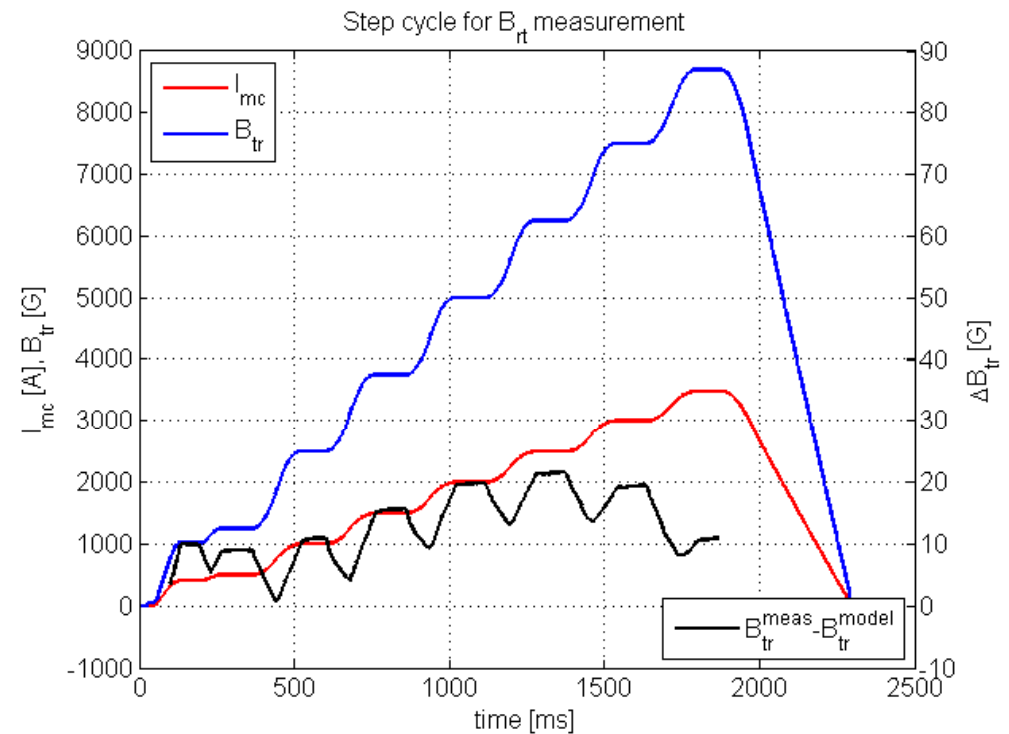
	Focusing half-unit			Defocusing half-unit		
	Dipole [T]	Quadrupole [T/m]	Sextupole [T/m ²]	Dipole [T]	Quadrupole [T/m]	Sextupole [T/m ²]
measured	0.16688	0.68500	0.25000	0.16712	-0.68600	0.15000
modelled	0.16659	0.68448	-0.00926	0.16662	-0.68574	-0.00144
difference	0.00029	0.00052	0.25926	0.00050	-0.00026	0.15144

- ▶ Cycle A comparison

	Focusing half-unit			Defocusing half-unit		
	Dipole [T]	Quadrupole [T/m]	Sextupole [T/m ²]	Dipole [T]	Quadrupole [T/m]	Sextupole [T/m ²]
measured	0.65227	2.74050	1.20000	0.68388	-2.73200	-1.55000
modelled	0.65333	2.74896	1.17631	0.68395	-2.74027	-1.42816
difference	-0.00106	-0.00846	0.02369	-0.00007	0.00827	-0.12184

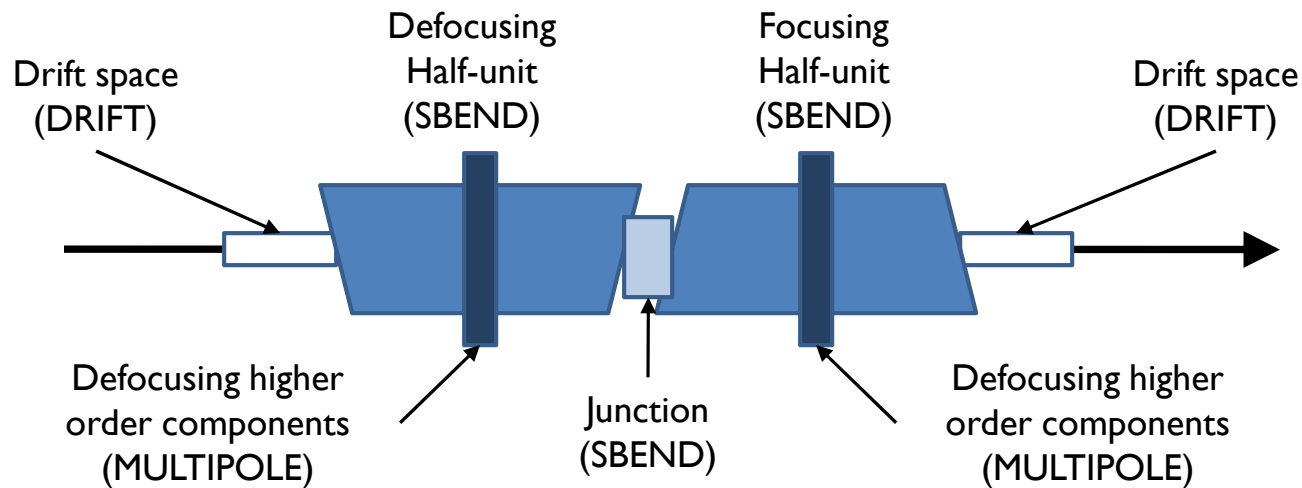
First comparison with measurement data

- ▶ Step cycle measurement and difference between measured and modelled field
 - ▶ Discrepancies up to 20 G
 - ▶ Dynamic and hysteresis effects are not yet included in the model
- ▶ Example of history dependent effect in SFTPRO cycle
 - ▶ Measured current difference corresponds to 5 G
 - ▶ Remanent field has to be investigated and implemented in the model



	Measured B_{tr} [G]	I_{mc} [A] Alone in SC	I_{mc} [A] Full SC	Estimated $ \Delta B_{tr} $ [G]
Injection	1013.7	404.9	404.5	1
Flat-top	6666	2668.08	2666	5

Magnet representation in the optical model



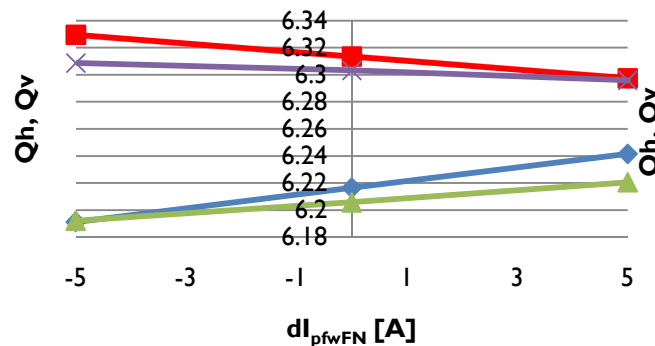
- ▶ Drift spaces under the main coil
- ▶ Focusing and defocusing sector magnet
 - ▶ Bending angle
 - ▶ Quadrupole and sextupole components – from magnetic model
 - ▶ Pole-face angles – no data available
 - ▶ Effective bending length – from old measurements
- ▶ Thin-lens multipoles
 - ▶ Octupole and higher components
 - ▶ Currently inactive
- ▶ Central junction
 - ▶ Quadrupole and sextupole component
 - ▶ Data unavailable

Tune calculation with MADX and field model

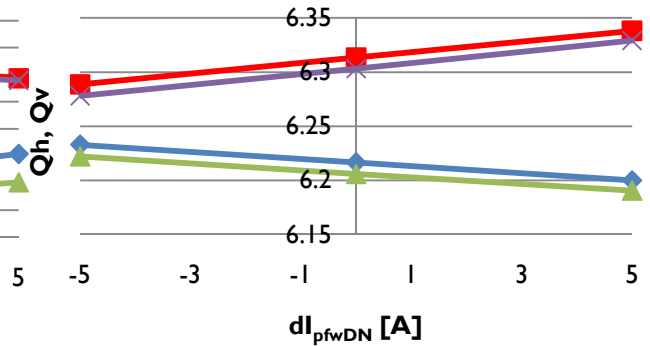
▶ Working point:

- ▶ $p = 14 \text{ GeV}/c$
- ▶ $B_{tr} = 6666.6 \text{ G}$
- ▶ $I_{f8} = 543.3 \text{ A}$
- ▶ $I_{pfwF} = 43.5 \text{ A}$
- ▶ $I_{pfwD} = -52.6 \text{ A}$

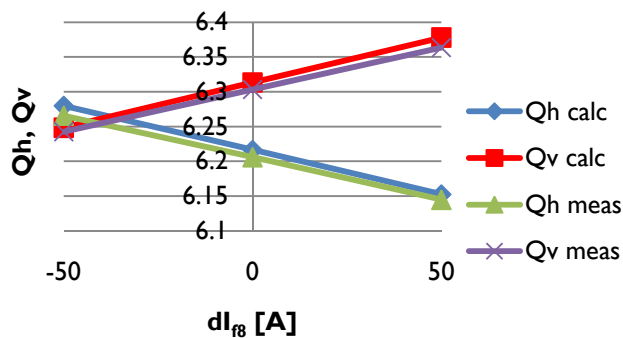
Tune vs PFW FN current variation



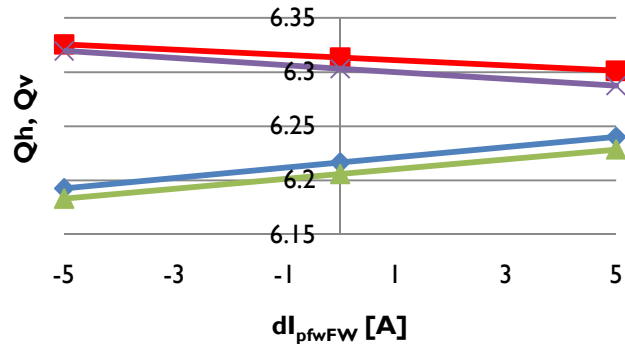
Tune vs PFW DN current variation



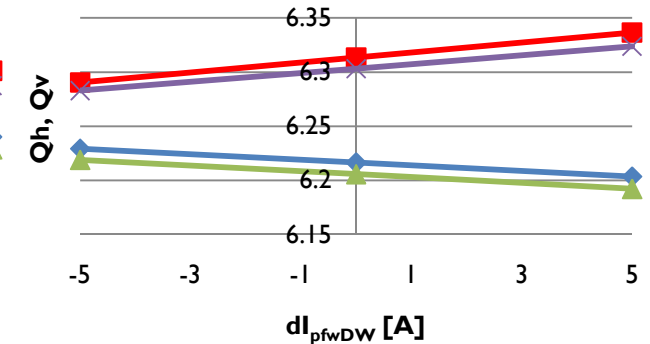
Tune vs Fo8 current variation



Tune vs PFW FW current variation



Tune vs PFW DW current variation



- ▶ Possibility to interpolate measurements for other working points and improve procedures controlling the beam parameters



Aspects of the optical model that need further work

- ▶ Effective bending and focusing length
- ▶ Pole-face angles (edge focusing)
- ▶ Field inside junction area
 - ▶ 3D modelling and magnetic measurements

- ▶ Degradation of optical parameters at stabilised field
 - ▶ Transient analysis
 - ▶ Real-time magnetic measurements
 - ▶ Beam based measurements



Scheme of work

	2009	2010			2011			2012			
Literature review	■	■	■								
Development of 2D numerical model and performing quasi-static simulation campaign		■	■								
Analysing data and formulating a 2D mathematical model		■	■	■	■						
Real-time magnetic measurements, verification and calibration of the model					■	■	■				
Beam measurements (tune and chromaticity)					■	■	■	■	■	■	■
Transient analysis of the field and model extension					■	■	■				
3D model development and 3D effects investigation						■	■	■	■		
Major measurement campaign on one of the spare magnets								■	■	■	■
Implementation in an optics model of the accelerator, recreation of beam parameters and validation with a beam-based measurements					■	■	■	■	■	■	
Implementation in accelerator control system										■	■
Evaluation of the presented approach in modelling other resistive magnets											■
Writing thesis										■	■